

# Non-Strongly Stable Orders and Simulation Relations

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# Motivation

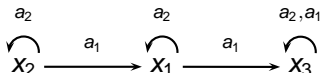
- We present two notions of simulation (those in Ignacio's talk) which can be defined as coalgebraic simulations.
  - Covariant-contravariant simulation: I/O Automata.
  - Conformance simulation: reducing non-determinism.
- In order to define them in a proper way we need an order with good enough properties.

# Coalgebraic Simulations

- Generalize coalgebraic bisimulations by means of arbitrary preorder relations.
- Very general notion; perhaps, **too general**: the induced similarity relation needs not be transitive.
- In [HughesJacobs04] **stability** is also required, which is guaranteed by a stronger condition (“right-stability”).
  - We have shown that it induces a “natural” direction in the induced simulation order.
  - However, the symmetric “left-stability” also guarantees stability.
  - Other, more elaborated “combinations” of right and left stable orders also do the work.

# Coalgebras

- For a functor  $F$ , an  $F$ -coalgebra is a function  $c : X \rightarrow FX$ , so that  $x \in X$  is a state and  $c(x)$  the set of successors of  $x$ .
- Choosing  $F$  we can obtain different structures:
  - ▶  $\mathcal{P}(X)^A$  for labelled transitions systems.



★  $X = \{x_1, x_2, x_3\}$ .

★  $c : X \rightarrow \mathcal{P}(X)^{\{a_1, a_2\}}$

$$c(x_1) : \{a_1, a_2\} \rightarrow \mathcal{P}(X)$$

$$c(x_1)(a_1) = \{x_3\}$$

$$c(x_1)(a_2) = \{x_1\}$$

- ▶  $\mathcal{P}(AP) \times \mathcal{P}(X)$  for Kripke structures.

# Bisimulations

- A functor  $F : \mathbf{Sets} \rightarrow \mathbf{Sets}$  can be lifted to  $\mathbf{Rel}(F) : \mathbf{Rel} \rightarrow \mathbf{Rel}$ :

$$\mathbf{Rel}(F)(R) = \{ \langle u, v \rangle \in FX_1 \times FX_2 \mid \exists w \in F(R). F(r_1)(w) = u, F(r_2)(w) = v \}$$

If  $R \subseteq X \times Y$  then  $\mathbf{Rel}(F)(R) \subseteq FX \times FY$ .

- A **bisimulation** for  $c : X \rightarrow FX$  and  $d : Y \rightarrow FY$  is a relation  $R \subseteq X \times Y$  “closed under  $c$  and  $d$ ”:

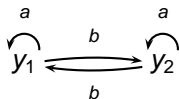
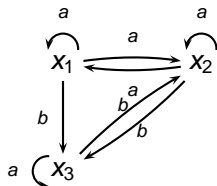
$$\text{if } (x, y) \in R \text{ then } (c(x), d(y)) \in \mathbf{Rel}(F)(R)$$

If states  $x$  and  $y$  are related, so are their successors  $c(x)$  and  $d(y)$ .

## Example: labelled transition systems

- Unfolding  $\text{Rel}(\mathcal{P}(\text{id})^A)(R) \subseteq \mathcal{P}(X)^A \times \mathcal{P}(Y)^A$ :

$$\text{Rel}(\mathcal{P}(\text{id})^A)(R) = \{(f, g) \mid \text{for all } a \in A, \\ \forall u \in f(a). \exists v \in g(a). uRv \wedge \\ \forall v \in g(a). \exists u \in f(a). uRv\}$$



$$c(x_1)(a) = \{x_1, x_2\}$$

$$c(x_1)(b) = \{x_3\}$$

$$d(y_2)(a) = \{y_2\}$$

$$d(y_2)(b) = \{y_1\}$$

- $R = \{(x_1, y_2), (x_2, y_2), (x_3, y_1)\}$ .
- $(c(x_1), d(y_2)) \in \text{Rel}(F)(R)$  but  $(c(x_2), d(y_1)) \notin \text{Rel}(F)(R)$ .

# Simulations

- An **order  $\sqsubseteq$  on  $F$**  is given by a collection  $\sqsubseteq_X \subseteq FX \times FX$  that is functorial (roughly, it must be preserved by renaming).
- A  **$\sqsubseteq$ -simulation** for  $c : X \rightarrow FX$  and  $d : Y \rightarrow FY$  is a relation  $R \subseteq X \times Y$  such that

$$\text{if } (x, y) \in R \text{ then } (c(x), d(y)) \in \text{Rel}_{\sqsubseteq}(F)(R),$$

that is,

$$c(x) \sqsubseteq_X u \text{ Rel}(F)(R) v \sqsubseteq_Y d(y),$$

for some  $u$  and  $v$ .

- Bisimulations are simulations for the identity order.

# Stability

- $\sqsubseteq$  for  $F$  is **stable** if  $\text{Rel}_{\sqsubseteq}(F)$  commutes with substitution:
  - Given  $f : X \rightarrow Z$  and  $g : Y \rightarrow W$ ,

$$\text{Rel}_{\sqsubseteq}(F)((f \times g)^{-1}(R)) = (Ff \times Fg)^{-1}(\text{Rel}_{\sqsubseteq}(F)(R))$$

- Stable orders give rise to nice simulations.
- $\sqsubseteq$  is **right-stable** if  $(id \times Ff)^{-1} \sqsubseteq_Y \subseteq \coprod_{Ff \times id} \sqsubseteq_X$ .
- Right-stability is equivalent to
  - $\sqsubseteq$  stable and
  - $\text{Rel}(F)(R) \circ \sqsubseteq_X \subseteq \sqsubseteq_Y \circ \text{Rel}(F)(R)$ .
- If  $F$  is right-stable,

$$\sqsubseteq_Y \circ \text{Rel}(F)(R) \circ \sqsubseteq_X = \sqsubseteq_Y \circ \text{Rel}(F)(R)$$



# Plain Simulation

- Labelled transition systems (lts) are coalgebras for the functor  $FX = \mathcal{P}(X)^A$ .
- “Classical” simulations coincide with coalgebraic simulations for the order  $\sqsubseteq$ :
  - ▶ given  $f, g \in FX = \mathcal{P}(X)^A$ , that is,  $f, g : A \rightarrow \mathcal{P}(X)$   
 $f \sqsubseteq g$  if for all  $a \in A$ ,  $f(a) \subseteq g(a)$ .
- It is right-stable.

# Plain Simulation

- As a consequence of the right-stability  $\sqsubseteq$ -simulations can be characterized as the  $(\sqsubseteq_Y \circ \text{Rel}(F)(R))$ -coalgebras.
  - ▶ The use of  $\sqsubseteq_X$  at the lhs can be replaced by that of  $\sqsubseteq_Y$  at the rhs:
    - $\sqsubseteq_X$  “adds new successors to  $c(x)$ ”.
    - $\sqsubseteq_Y$  “removes successors of  $d(y)$ ”.
    - If  $q$  simulates  $p$ , by removing the exceeding part of  $q$  we obtain  $q''$  “bisimilar” to  $p$ .

$$p \text{ Rel}(F)(R) q'' \sqsubseteq q$$

# Anti-simulations

- Anti-simulations are  $\supseteq$ -simulations for  $FX = \mathcal{P}(X)^A$ , that is,

$$f \sqsubseteq g \Leftrightarrow f(a) \supseteq g(a) \text{ for all } a \in A.$$

- $c$  “simulates”  $d$  if and only if  $d$  “is simulated by”  $c$ .
- The order  $\supseteq$  is **not right-stable**.
- However, it is stable.

# Left-stability

- $F$  with  $\sqsubseteq$  is **left-stable** if for all  $f : X \rightarrow Y$ ,

$$(Ff \times id)^{-1} \sqsubseteq_Y \subseteq \coprod_{id \times Ff} \sqsubseteq_X .$$

- Anti-simulation is left-stable.
- $F$  with  $\sqsubseteq$  is stable iff it is stable with the inverse order  $\sqsubseteq^{op}$ .

# Relating (Trivially) Left-stable and Right-stable Orders

- An order  $\sqsubseteq$  is left-stable iff  $\sqsubseteq^{op}$  is right-stable.
  - Both right-stability and left-stability give a **natural** direction to simulation relations.
- Left-stable orders have the same structural properties as right-stable ones.
  - ▶  $\sqsubseteq$ -similarity is transitive, etc.
- The composition of right (resp. left)-stable orders gives us a new right (resp. left)-stable order.

# Covariant-contravariant simulations

- Given an alphabet  $Act$ , we will consider a partition  $\{Act^r, Act^l, Act^{bi}\}$  of  $Act$ .
- An  $(Act^r, Act^l)$ -**simulation** for  $c : X \longrightarrow \mathcal{P}(X)^{Act}$  and  $d : Y \longrightarrow \mathcal{P}(Y)^{Act}$  is a relation  $S$  such that  $\forall (x, y) \in S$ :
  - ▶  $\forall a \in Act^r \cup Act^{bi}, \forall x \xrightarrow{a} x' \exists y \xrightarrow{a} y'$  with  $(x', y') \in S$ .
  - ▶  $\forall a \in Act^l \cup Act^{bi}, \forall y \xrightarrow{a} y' \exists x \xrightarrow{a} x'$  with  $(x', y') \in S$ .

# Covariant-contravariant simulations

- $(Act^r, Act^l)$ -simulations can be defined as the coalgebraic simulations for the order  $Act^r \sqsubseteq_{Act^l} \subseteq \mathcal{P}(X)^A \times \mathcal{P}(X)^A$ .
- If  $f, g : Act \longrightarrow \mathcal{P}(X)$ , then  $f \sqsubseteq_{Act^r \sqsubseteq_{Act^l}} g \Leftrightarrow$ :
  - ▶ for all  $a \in Act^r \cup Act^{bi}$ ,  $f(a) \subseteq g(a)$ , and
  - ▶ for all  $a \in Act^l \cup Act^{bi}$ ,  $f(a) \supseteq g(a)$ .
- $Act^r \sqsubseteq_{Act^l}$  is stable.
  - ▶ It can be “decomposed” as a product of both right-stable and left-stable orders.
  - ▶ However, it is neither right-stable nor left-stable.

# Conformance simulations

- They behave as plain simulations allowing the extension of the set of actions offered by a process:

$$a < a + b$$

- But a process can also be “improved” by reducing the nondeterminism in it.

$$ap + aq < ap$$

- A **conformance simulation** between  $c : X \longrightarrow \mathcal{P}(X)^A$  and  $d : Y \longrightarrow \mathcal{P}(Y)^A$ , is a relation  $R$  such that if  $pRq$  then

- ▶  $\forall a \in A, p \xrightarrow{a} \Rightarrow q \xrightarrow{a}$ .
- ▶  $\forall a \in A (q \xrightarrow{a} q' \wedge p \xrightarrow{a}) \Rightarrow p \xrightarrow{a} p' \text{ and } p'Rq'$ .



# Conformance simulations

- Conformance simulations can be defined as the coalgebraic simulations for the order  $\sqsubseteq^{Conf} \subseteq \mathcal{P}(X)^A \times \mathcal{P}(X)^A$ .
- If  $f, g : A \longrightarrow \mathcal{P}X$ , then  $f \sqsubseteq_X^{Conf} g \Leftrightarrow$ 
  - ▶ Either  $f(a) = \emptyset$ , or
  - ▶  $f(a) \supseteq g(a)$  and  $g(a) \neq \emptyset$ .
- $\sqsubseteq^{Conf}$  is stable.
  - ▶ However, it is neither right-stable nor left-stable.

## Side stable orders

- In the proof of stability of the order for covariant-contravariant simulations, each subset of the partition of  $Act$  is dealt with separately.
- An order  $\sqsubseteq$  defined over  $F^A$  may be split into a family of orders  $\sqsubseteq^a$  over  $F$ .
- An order  $\sqsubseteq$  over a functor  $F^A$  is **action-distributive** if there exists a family of orders  $\sqsubseteq^a$  on  $F$  such that:

$$f \sqsubseteq g \iff f(a) \sqsubseteq^a g(a)$$

for all  $a \in A$ . We write  $\sqsubseteq = \prod_{a \in A} \sqsubseteq^a$ .

# Side stable orders

- A **side stable order** is an action-distributive order such that each component is either right-stable or left-stable.
- If  $\sqsubseteq = \prod_{a \in A} \sqsubseteq^a$  and each  $\sqsubseteq^a$  is stable, then  $\sqsubseteq$  is also stable.
  - ▶ Side stable orders are stable.
- By separating the right and the left-stable components we obtain  $\sqsubseteq = (\sqsubseteq^{\bar{r}} \cup \sqsubseteq^l)^*$ .
- The covariant-contravariant order  $_{Act^r} \sqsubseteq_{Act^l}$  is side stable.

# Composition of Right-stable and Left-stable Orders

- $\sqsubseteq^{Conf}$  is also an action-distributive order, but not side stable.
- The distributivity of  $\sqsubseteq^{Conf}$  leads to its decomposition as a right-stable and a left-stable order that commute with each other.
- Given  $\sqsubseteq^r$  that is right-stable on  $F$  and  $\sqsubseteq^l$  that is left-stable, and commute with each other, their composition defines a stable order on  $F$ .
- Moreover, the coalgebraic simulations for  $\sqsubseteq = \sqsubseteq^r \circ \sqsubseteq^l$  can be characterized as the  $(\sqsubseteq^r \circ \text{Rel}(F)(R) \circ \sqsubseteq^l)$ -coalgebras.

# Logical Characterizations

- We are interested in finding modal logics that characterize these two notions of simulations.
- A first approach is to build them from scratch taking, for example, plain simulations as models.
- A second way is to follow the general categorical constructions developed by Corina Cîrstea.

# Logical Characterizations: the Categorical Way

- First, the adequate order has to be identified. Actually, Cîrstea's construction follows an alternative presentation of coalgebraic simulations.
- The language of the logic is the initial algebra of a suitable functor.
- The “semantics” of the logic is defined by means of another functor.
- Under certain conditions (a colimit needs to exist), the “semantics” induces a logic that characterizes similarity for the simulation.
- We were able to check that the logics obtained for our simulations using these two methods coincide.

# Summary

- Two interesting notions of coalgebraic simulations which are not strongly stable.
  - ▶ Both can be factorized into the composition of a right and a left-stable component, and so are proved to be stable.
  - ▶ Witness that “strong” stability is, well, too strong.
- Right-stability is an asymmetric property.
  - ▶ We can use it to get a natural orientation for the simulation orders.
  - ▶ Its dualization leads to left-stability, with the same good properties.
  - ▶ By combining both right-stable and left-stable orders in several ways we can still preserve stability.
- These simulations can be endowed with a modal logic that characterizes them.
  - ▶ Ad-hoc manner.
  - ▶ Categorically.